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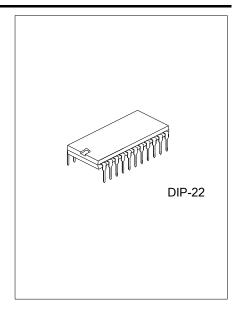
RCR5 **CMOS IC Preliminary**

REMOTE CONTROLLER WITH NINE FUNCTIONS

DESCRIPTION

The UTC RCR5 is a CMOS LSI and designed as receiver that complement to UTC RCT5 for remote controlled car applications. It provide nine control keys controlling the motions, which are forward, backward, rightward, leftward, four function keys, and the turbo function, of the remote controlled car.

UTC RCR5 have Forward (Backward) combined with the turbo application. During normal operation without Turbo, Forward (Backward) output from UTC RCR5 sends a 60Hz signal. When Forward (Backward) and Turbo are both in effect, the output signal becomes completely high.

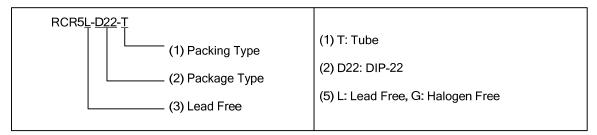


FEATURES

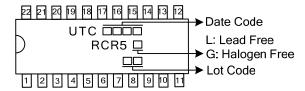
- * Operating voltage range: 2.4V~4.0V
- * Built-in 4.2V zener
- * Few external components needed
- * 9-function remote controller controlling Forward/ Backward/ Turbo/ Right-turn/ Left turn/ four function keys
- * Complement to UTC RCT5.

ORDERING INFORMATION

| Orderi | ng Number | Dookogo | Dooking |
|-------------|--------------|---------|---------|
| Lead Free | Halogen Free | Package | Packing |
| RCR5L-D22-T | RCR5G-D22-T | DIP-22 | Tube |

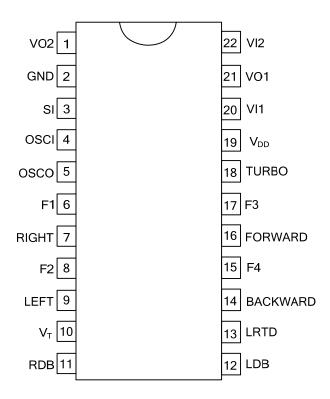


MARKING



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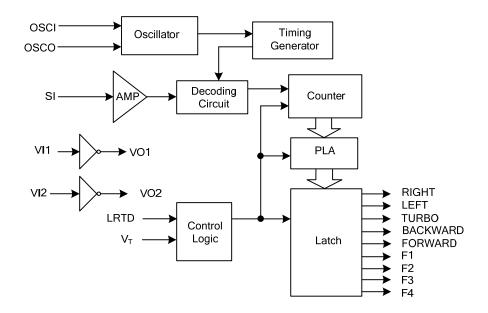
■ PIN CONFIGURATIONS



■ PIN DESCRIPTION

| PIN NO. | PIN NAME | DESCRIPTION |
|---------|----------|---|
| 1 | VO2 | Inverter 2 output pin for signal amplify |
| 2 | GND | Ground |
| 3 | SI | Input pin of the encoding signal |
| 4 | OSCI | Oscillator input pin |
| 5 | OSCO | Oscillator output pin |
| 6 | F1 | F1 function output pin |
| 7 | RIGHT | Rightward output pin |
| 8 | F2 | F2 function output pin |
| 9 | LEFT | Leftward output pin |
| 10 | V_{T} | Auto Shut-OFF input pin. If V_T voltage exceeds 1.4V, all outputs shut off automatically. |
| 11 | RDB | Right disable pin. |
| 12 | LDB | Left disable pin. |
| 13 | LRTD | Left/right turbo disable pin |
| 14 | BACKWARD | Backward output pin |
| 15 | F4 | F4 function output pin |
| 16 | FORWARD | Forward output pin |
| 17 | F3 | F3 function output pin |
| 18 | TURBO | TURBO output pin |
| 19 | V_{DD} | Power supply |
| 20 | VI1 | Inverter 1 input pin for signal amplify |
| 21 | VO1 | Inverter 1 output pin for signal amplify |
| 22 | VI2 | Inverter 2 input pin for signal amplify |

■ BLOCK DIAGRAM



| Innut Condition | O/P Condition | | | | | | |
|------------------|---------------|----------|-------|--|--|--|--|
| Input Condition | Forward | Turbo | | | | | |
| Forward | илл=60Hz | Low | Low | | | | |
| Backward | Low | ллл=60Hz | Low | | | | |
| Forward + turbo | =high | Low | =high | | | | |
| Backward + turbo | Low | =high | =high | | | | |

An Auto Shut-Off mechanism is built-in according to Toy Safety Requirement and effective during over-current situation in motor driver. The active high input applying to this Auto Shut-Off pin will turn off the motor. (V_T pin, when unused, has to be connected to ground. The transfer point =1.4V)

■ ABSOLUTE MAXIMUM RATINGS

| PARAMETER | SYMBOL | RATINGS | UNIT |
|-----------------------|------------------|-------------------------------|------|
| DC Supply Voltage | V_{DD} | 2.4~4.0 | V |
| Input/Output Voltage | | GND-0.2~ V _{DD} +0.2 | V |
| Operating Temperature | T_OPR | -10~+60 | °C |
| Storage Temperature | T _{STG} | -25~+125 | °C |

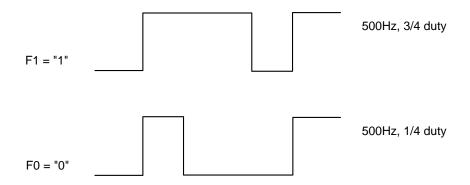
Note: Absolute maximum ratings are those values beyond which the device could be permanently damaged. Absolute maximum ratings are stress ratings only and functional device operation is not implied.

■ **ELECTRICAL CHARACTERISTICS** (T_A=25°C, V_{DD}=3.0V, Fosc=128KHz, unless otherwise specified.)

Direct Driving: No connect a resistance between POWER and IC's V_{DD} pin.

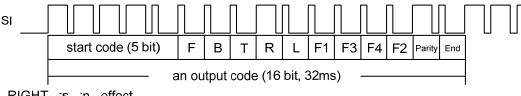
| PARAMETER | SYMBOL | TEST CONDITIONS | MIN | TYP | MAX | UNIT |
|---------------------------------------|------------------------|-----------------------|-----|-----|-----|------|
| Operating Voltage | V_{OPR} | | 2.4 | 3.0 | 4.0 | V |
| Operating Current | I _{OPR} | Unload | 0.2 | 0.4 | 1.0 | mA |
| O/P Driving Current | I _{DRIVE} | V _{OH} =0.7V | 5.0 | | | mA |
| O/P Driving Current (F1, F2) | I _{DRIVE} | V _{OH} =0.7V | 5.0 | | | mA |
| Effect Decoding (Frequency Variation) | F _{TOLERANCE} | | -50 | | 50 | % |
| Oscillator Frequency | Fosc | | | 128 | | KHz |
| Oscillator Frequency Tolerance | Ftolerance | UTC RCT5 FOSC=128KHz | -20 | | +20 | % |

DATA FORMAT



CODING METHOD

The data string that UTC RCR5 receiver is below:



RIGHT :s :n effect

Data string: start code + data code + parity code + end code

- start code = F1 F1 F1 F1 F0

| - data code = | F | В | Т | R | L | F1 | F3 | F4 | F2 |
|---------------|---|---|---|---|---|----|----|----|----|
|---------------|---|---|---|---|---|----|----|----|----|

F = ForwardB = Backward T = TurboR = RightL = Left F1 = Function 1 F2 = Function 2 F3 = Function 3 F4 = Function 3

F、B、T、R、L、F1、F3、F4、F2 all can have two date format, "F1" or "F0",

"F1" means the function is in effect, and "F0" means not.

- parity code = for parity check
- end code = for (latch data)

^{*} Data code can be any combination of F, B, T, R, L, F1, F2, F3, F4 except for F & B, and R & L

■ OUTPUT TABLES

| FUNCTION | OUTPUT STATUS | | | | | | | | | |
|--|---------------|---|-----|--|----|------|----|----|----|--|
| FUNCTION | F | В | T | R | L | F1 | F2 | F3 | F4 | |
| FORWARD | Н | | | | | | | | | |
| LEFT + FORWARD | Н | | | | Н | | | | | |
| RIGHT + FORWARD | Н | | | Н | | | | | | |
| TURBO | | | Н | | | | | | | |
| TURBO + FORWARD | Н | | Н | | | | | | | |
| TURBO + LEFT + FORWARD | Н | | Н | | Н | | | | | |
| TURBO + RIGHT + FORWARD | Н | | Н | Н | | | | | | |
| BACKWARD | | Н | | | | | | | | |
| BACKWARD + RIGHT | | Н | | Н | | | | | | |
| BACKWARD + LEFT | | Н | | | Н | | | | | |
| TURBO + BACKWARD | | Н | Н | | | | | | | |
| TURBO + BACKWARD + RIGHT | | Н | н | Н | | | | | | |
| TRUBO + BACKWARD + LEFT | | Н | Н | | Н | | | | | |
| LEFT | | | | | Н | | | | | |
| RIGHT | | | | Н | | | | | | |
| FUNCTION1 | | | | | | Н | | | | |
| FORWARD + FUNCTION1 | Н | | | | | H '' | | | | |
| FORWARD + TURBO + FUNCTION1 | <u></u> Н | + | Н | | | Н Н | | | | |
| TURBO + FUNCTION1 | | | Н Н | 1 | | H '' | | | | |
| | | Н | | | | Н Н | | | | |
| BACKWARD + FUNCTION1 BACKWARD + TURBO + FUNCTION1 | | Н | ш | | | Н Н | | | | |
| LEFT + FORWARD + FUNCTION1 | Н | П | H | | Н | Н Н | | | | |
| | н | | | Н | "" | Н Н | | | | |
| RIGHT + FORWARD + FUNCTION1 | П | | | | Н | Н | | | | |
| LEFT + BACKWARD + FUNCTION1 | | H | | Н | П | | | | | |
| RIGHT + BACKWARD + FUNCTION1 | | Н | | | | H | | | | |
| LEFT + FUNCTION1 | | | | | Н | H | | | | |
| RIGHT + FUNCTION1 | | | | Н | | Н | | | | |
| FUNCTION2 | | | | | | | H | | | |
| FORWARD + FUNCTION2 | Н | | | | | | Н | | | |
| FORWARD + TURBO + FUNCTION2 | Н | | Н | | | | Н | | | |
| TURBO+ FUNCTION2 | | | Н | | | | H | | | |
| BACKWARD + FUNCTION2 | | Н | | | | | Н | | | |
| BACKWARD + TURBO + FUNCTION2 | | Н | Н | | | | H | | | |
| LEFT + FORWARD + FUNCTION2 | Н | | | | Н | | Н | | | |
| RIGHT + FORWARD + FUNCTION2 | Н | | | Н | | | Н | | | |
| LEFT + BACKWARD + FUNCTION2 | | Н | | | Н | | Н | | | |
| RIGHT + BACKWARD + FUNCTION2 | | Н | | Н | | | Н | | | |
| LEFT + FUNCTION2 | | | | | Н | | Н | | | |
| RIGHT + FUNCTION2 | | | | Н | | | Н | | | |
| FUNCTION3 | | | | | | | | н | | |
| FORWARD + FUNCTION3 | Н | | | | | | | н | | |
| FORWARD + TURBO + FUNCTION3 | Н | | Н | | | | | Н | | |
| | ••• | | | | | | | н | | |
| TURBO+ FUNCTION3 | | 1 | H | 1 | | | | | | |
| BACKWARD + FUNCTION3 | | Н | | 1 | | | | Н | | |
| BACKWARD + TURBO + FUNCTION3 | | Н | Н | 1 | | | | Н | | |
| LEFT + FORWARD + FUNCTION3 | Н | | | | Н | | | Н | | |
| RIGHT + FORWARD + FUNCTION3 | Н | | | Н | | | | Н | | |
| LEFT + BACKWARD + FUNCTION3 | | Н | | 1 | н | | | Н | | |
| | | 1 | | Н | '' | | | Н | | |
| RIGHT + BACKWARD + FUNCTION3 | | Н | | | | | | | | |

■ OUTPUT TABLES(Cont.)

| FUNCTION | OUTPUT STATUS | | | | | | | | | | |
|------------------------------|---------------|---|---|---|---|----|----|----|----|--|--|
| FONCTION | F | В | Т | R | L | F1 | F2 | F3 | F4 | | |
| LEFT + FUNCTION3 | | | | | Н | | | Н | | | |
| RIGHT + FUNCTION3 | | | | Н | | | | Н | | | |
| FUNCTION4 | | | | | | | | | Н | | |
| FORWARD + FUNCTION4 | Н | | | | | | | | Н | | |
| FORWARD + TURBO + FUNCTION4 | Н | | Н | | | | | | Н | | |
| TURBO+ FUNCTION4 | | | Н | | | | | | Н | | |
| BACKWARD + FUNCTION4 | | Η | | | | | | | Н | | |
| BACKWARD + TURBO + FUNCTION4 | | Н | Н | | | | | | Н | | |
| LEFT + FORWARD + FUNCTION4 | Н | | | | Н | | | | Н | | |
| RIGHT + FORWARD + FUNCTION4 | Н | | | Н | | | | | Н | | |
| LEFT + BACKWARD + FUNCTION4 | | Н | | | Н | | | | Η | | |
| RIGHT + BACKWARD + FUNCTION4 | | Н | | Н | | | | | Н | | |
| LEFT +FUNCTION4 | | | | | Н | | | | Н | | |
| RIGHT + FUNCTION4 | | | | Н | | | | | Н | | |

H = high level, Z = 60Hz flash, Blank=L

Thus, from the table, we can see that there are more than 50 states of function combinations from 7 control keys.

Notes: 1. LRTD pin functions as an option pin for LEFT/RIGHT turbo disable.

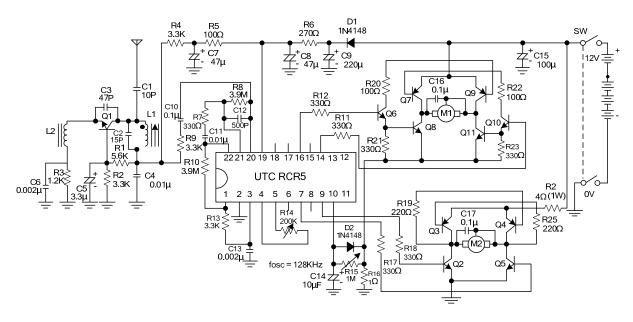
| "LRTD" | Key selected | Output Function |
|-------------|--------------------------------|--------------------------------|
| HIGH (OPEN) | FORWARD + LEFT (RIGHT) + TURBO | FORWARD + LEFT (RIGHT) + TURBO |
| LOW | FORWARD + LETT (RIGHT) + TURBO | FORWARD + LEFT (RIGHT) |

2. The UTC RCR5 have built in a zener diode, so you must add a resistance between POWER and IC's V_{DD} pin, like the R6 of UTC RCR5 application circuit.

■ TYPICAL APPLICATION CIRCUIT (FOR REFERENCE ONLY)

Receiver (UTC RCR5 Fosc

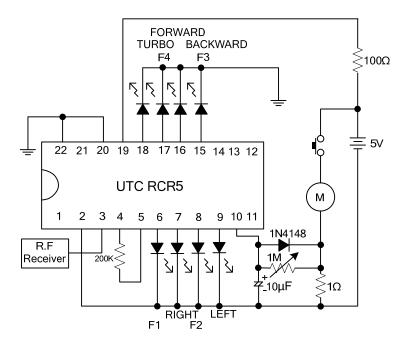
≤ 128KHz)



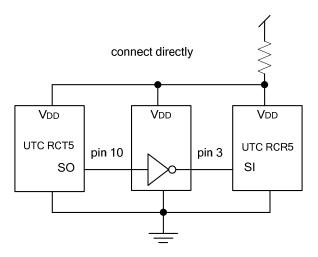
■ TEST CIRCUIT

Fosc for UTC RCR5

□ 128KHz



UTC RCT5 output pin (SO) has an inverted phase with UTC RCR5 input (SI). If UTC RCT5 is connected without using a R_F module, an inverter has to be inserted between this 2 pins.



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