

# UNISONIC TECHNOLOGIES CO., LTD

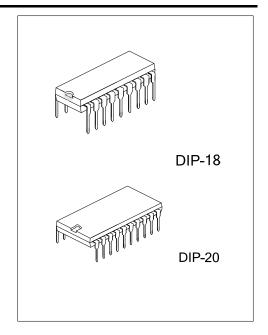
RCR6C Preliminary cmos ic

# REMOTE CONTROLLER WITH SEVEN FUNCTIONS

#### ■ DESCRIPTION

The UTC RCR6C is a CMOS LSI and designed as receiver that complement to UTC RCT6 for remote controlled car applications. It provide seven control keys controlling the motions, which are forward, backward, rightward, leftward, two function keys, and the turbo function, of the remote controlled car.

UTC RCR6C have Forward (Backward) combined with the turbo application. During normal operation without Turbo, Forward (Backward) output from UTC RCT6 sends a 60Hz signal. When Forward (Backward) and Turbo are both in effect, the output signal becomes completely high.

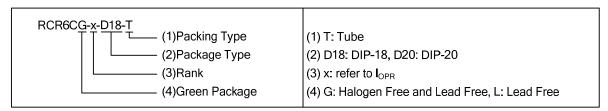


#### **■** FEATURES

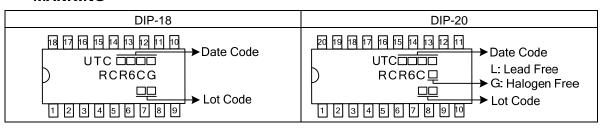
- \* Operating voltage range: 2.4V~4.5V
- \* RCR6C-A built-in 3.6V ZENER
  - RCR6C-B built-in 4.2V ZENER
  - RCR6C-C built-in 5.0V ZENER
- \* Few external components needed
- \* 7-function remote controller controlling Forward/ Backward/ Turbo/ Right-turn/ Left turn/ two function keys
- \* Complement to UTC RCT6.

#### **■** ORDERING INFORMATION

Order N	Dookogo	Dooking	
Lead Free	Halogen Free	Package	Packing
-	RCR6CG-x-D18-T	DIP-18	Tube
RCR6CL-x-D20-T	RCR6CG-x-D20-T	DIP-20	Tube

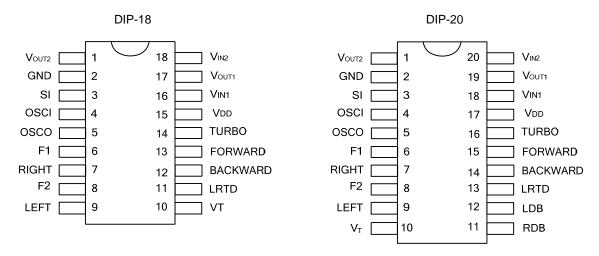


#### **■** MARKING



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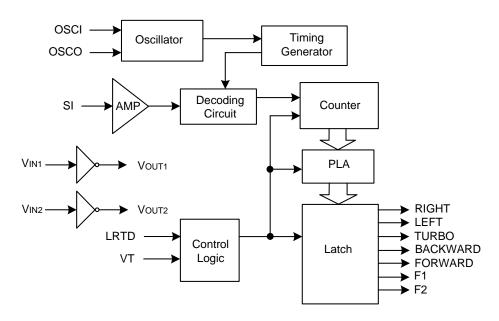
#### **■ PIN CONFIGURATIONS**



#### **■ PIN DESCRIPTION**

PIN NO.		DININIANAE	DESCRIPTION		
DIP-18	DIP-20	PIN NAME	DESCRIPTION		
1	1	$V_{OUT2}$	Inverter 2 output pin for power amplify		
2	2	GND	Negative power supply		
3	3	SI	Input pin of the encoding signal		
4	4	OSCI	Oscillator input pin		
5	5	OSCO	Oscillator output pin		
6	6	F1	F1 function output pin		
7	7	RIGHT	Rightward output pin		
8	8	F2	F2 function output pin		
9	9	LEFT	Leftward output pin		
10	10 10		Auto Shut-OFF input pin		
10	10	V <sub>T</sub>	If $V_T$ voltage exceeds 1.4V, all outputs shut off automatically.		
	11	RDB	With Pull-up resistor, rightward function disabled if this pin connected to GND		
	12	LDB	With Pull-up resistor, leftward function disabled if this pin connected to GND		
11	13	LRTD	If connect gnd ,Left/right+ turbo is disable		
12	14	BACKWARD	Backward output pin		
13	15	FORWARD	Forward output pin		
14	16	TURBO	TURBO output pin		
15	17	$V_{DD}$	Positive power supply		
16	18	$V_{IN1}$	Inverter 1 input pin for signal amplify		
17	19	$V_{OUT1}$	Inverter 1 output pin for signal amplify		
18	20	$V_{IN2}$	Inverter 2 input pin for signal amplify		

# ■ BLOCK DIAGRAM



Input	O/P Condition			
Condition	Forward	Backward	Turbo	
Forward	⊔ЛЛЛ= <b>60H</b> z	Low	Low	
Backward	Low	-7-77-=60Hz	Low	
Forward + turbo	=high	Low	=high	
Backward + turbo	Low	=high	=high	

Note: An Auto Shut-Off mechanism is built-in according to Toy Safety Requirement and effective during over-current situation in motor driver. The active high input applying to this Auto Shut-Off pin will turn off the motor. ( $V_T$  pin, when unused, has to be connected to ground. The transfer point =1.4V)

#### ■ ABSOLUTE MAXIMUM RATINGS

PARAMETER	SYMBOL	RATINGS	UNIT
DC Supply Voltage	$V_{DD}$	2.4~4.5	V
Input/Output Voltage		GND-0.2~ V <sub>DD</sub> +0.2	V
Operating Temperature	$T_{OPR}$	-10~+60	°C
Storage Temperature	T <sub>STG</sub>	-25~+125	°C

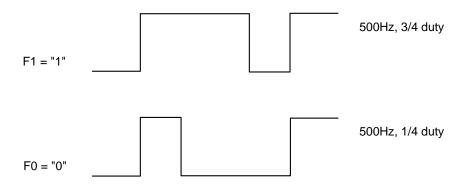
Note: Absolute maximum ratings are those values beyond which the device could be permanently damaged. Absolute maximum ratings are stress ratings only and functional device operation is not implied.

# ■ **ELECTRICAL CHARACTERISTICS** (T<sub>A</sub>=25°C, V<sub>DD</sub>=3.5V, F<sub>OSC</sub>=128KHz, unless otherwise specified.)

Direct Driving: No connect a resistance between POWER and IC's V<sub>DD</sub> pin.

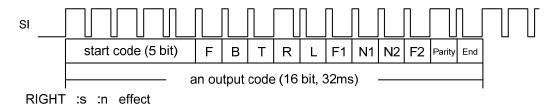
PARAMETER	SYMBOL	TEST CONDITIONS		MIN	TYP	MAX	UNIT
Operating Voltage	$V_{OPR}$			2.4		4.5	V
			RCR6C-A			15	
Supply Current	I <sub>DD</sub>	Unload	RCR6C-B			0.6	mA
			RCR6C-C			0.5	
O/P Driving Current	I <sub>DRIVE</sub>	V <sub>OH</sub> =0.7V		5.0			mA
O/P Driving Current (F1, F2)	I <sub>DRIVE</sub>	V <sub>OH</sub> =0.7V		5.0			mA
Effect Decoding (Frequency Variation)	F <sub>TOLERANCE</sub>			-50		50	%
Oscillator Frequency	Fosc				128		KHz
Oscillator Frequency Tolerance	Ftolerance	UTC RCT6 FOSC=128KHz		-20		+20	%

#### **■ DATA FORMAT**



#### **■ CODING METHOD**

The data string that UTC RCR6C receiver is below:



Data string: start code + data code + parity code + end code

```
- start code = F1 F1 F1 F1 F0
- data code = F B T R L F1 N N F2
```

F2 = Function 2 N = No used code

F、B、T、R、L、F1、N、N、F2 all can have two date format, "F1" or "F0",

"F1" means the function is in effect, and "F0" means not.

- parity code = for parity check
- end code = for (latch data)
- \* Data code can be any combination of F, B, T, R, L, F1, F2, except for F & B, and R & L

# ■ OUTPUT TABLES

FLINCTION		OUTPUT STATUS						
FUNCTION	F	В	Т	R	L	F1	F2	
FORWARD	Z							
LEFT+FORWARD	Z				Н			
RIGHT+FORWARD	Z			Н				
TURBO			Н					
TURBO+FORWARD	Н		Н					
TURBO+LEFT+FORWARD	Н		Н		Н			
TURBO+RIGHT+FORWARD	Н		Н	Н				
BACKWARD		Z						
BACKWARD+RIGHT		Z		Н				
BACKWARD+LEFT		Z			Н			
TURBO+BACKWARD		Н	Н					
TURBO+BACKWARD+RIGHT		Н	Н	Н				
TURBO+BACKWARD+LEFT		Н	Н		Н			
LEFT					Н			
RIGHT				Н				
FUNCTION1						Н		
FORWARD+FUNCTION1	Z					Н		
FORWARD+TURBO+FUNCTION1	Н		Н			Н		
TURBO+FUNCTION1			Н			Н		
BACKWARD+FUNCTION1		Z				Н		
BACKWARD+TURBO+FUNCTION1		Н	Н			Н		
LEFT+FORWARD+FUNCTION1	Z				Н	Н		
RIGHT+FORWARD+FUNCTION1	Z			Н		Н		
LEFT+BACKWARD+FUNCTION1		Z			Н	Н		
RIGHT+BACKWARD+FUNCTION1		Z		Н		Н		
LEFT+FUNCTION1					Н	Н		
RIGHT+FUNCTION1				Н		Н		
FUNCTION2							Н	
FORWARD+FUNCTION2	Z						Н	
FORWARD+TURBO+FUNCTION2	Н		Н				Н	
TURBO+FUNCTION2			Н				Н	
BACKWARD+FUNCTION2		Z					Н	
BACKWARD+TURBO+FUNCTION2		Н	Н				Н	
LEFT+FORWARD+FUNCTION2	Z				Н		Н	
RIGHT+FORWARD+ FUNCTION2	Z			Н			Н	
LEFT+BACKWARD+FUNCTION		Z			Н		Н	
RIGHT+BACKWARD+FUNCTION2		Z		Н			Н	
LEFT+FUNCTION					Н		Н	
RIGHT+FUNCTION2				Н			Н	

H = high level, Z = 60Hz flash, Blank=L

Thus, from the table, we can see that there are more than 50 states of function combinations from 7 control keys.

### ■ NOTE

(1) LRTD pin functions as an option pin for LEFT/RIGHT turbo disable.

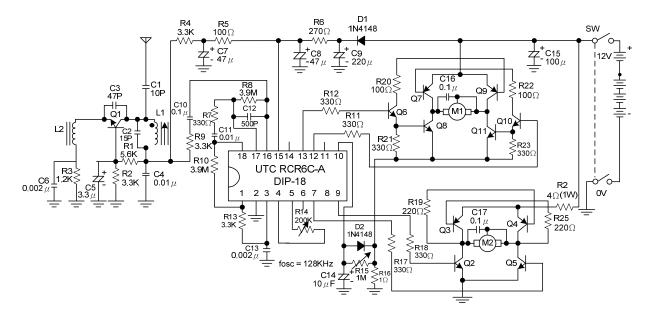
(1) = (1) = (1) = (1) = (1)				
"LRTD"	Key selected	Output Function		
HIGH (OPEN)	FORWARD + LEFT (RIGHT) + TURBO	FORWARD + LEFT (RIGHT) + TURBO		
LOW	FORWARD + LETT (RIGHT) + TURBO	FORWARD + LEFT (RIGHT)		

<sup>(2)</sup> The UTC RCR6C have built in a zener diode, so you must add a resistance between POWER and IC's  $V_{DD}$  pin, like the R6 of UTC RCR6C application circuit.



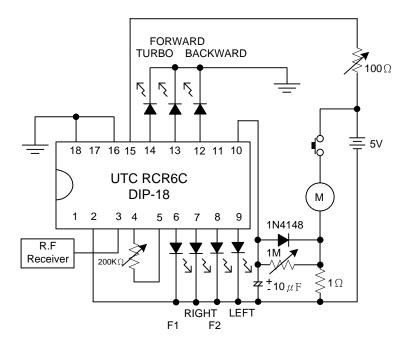
# ■ TYPICAL APPLICATION CIRCUIT (FOR REFERENCE ONLY)

Receiver (UTC **RCR6C DIP-18** Fosc ≌ 128KHz)

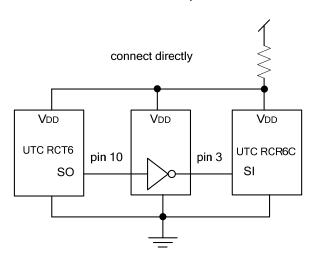


#### ■ TEST CIRCUIT

Fosc for UTC RCR6C ≅ 128KHz



UTC RCT6 output pin (SO) has an inverted phase with UTC RCR6C input (SI). If UTC RCT6 is connected without using a  $R_F$  module, an inverter has to be inserted between this 2 pins.



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